

*Reprinted from*

# **Applied Electromagnetics** in **Materials**

*Proceedings of the First International Symposium  
Tokyo, 3-5 October 1988*

Edited by

**K. MIYA**

Nuclear Engineering Research Laboratory  
Faculty of Engineering, University of Tokyo, Japan



**PERGAMON PRESS**

OXFORD · NEW YORK · BEIJING · FRANKFURT  
SÃO PAULO · SYDNEY · TOKYO · TORONTO

# Faster Eddy Current Computation Using Voronoi-Delaunay Transformation

Y. SAITO, S. IKEGUCHI and S. HAYANO

*College of Engineering, Hosei University,  
3-7-2 Kajinocho Koganei, Tokyo 184, Japan*

## ABSTRACT

Previously, we have proposed a locally orthogonal discretization method based on a Voronoi-Delaunay diagram for calculating the electromagnetic fields in a most efficient manner (Saito *et al.*, 1986, 1988, 1989). This locally orthogonal discretization method has been compelled to solve the two-independent systems (Voronoi and Delaunay). However, in this paper, we exploit the Voronoi-Delaunay transformation method that the solution of Delaunay system can be obtained by transforming the solution of Voronoi system. This Voronoi-Delaunay transformation method is now applied to the transient eddy current problems. As a result, it is found that the eddy current problems can be solved by means of the Voronoi-Delaunay transformation in an extremely efficient manner.

## KEYWORDS

Eddy current; Field computation; Voronoi-Delaunay;

## INTRODUCTION

In order to evaluate the electromagnetic fields in a most efficient manner, a geometrical duality between the Delaunay triangles and associated Voronoi polygons has been utilized to implement a dual energy finite element approach (Saito *et al.*, 1986, 1988, 1989). This method requires the use of a single potential to establish the upper and lower bounds of solutions, whereas the traditional dual energy finite element approach requires the use of two different types of potentials (vector and scalar) (Penman *et al.*, 1982, Hammond *et al.*, 1976, 1983). Therefore it is obvious that this method is able to provide the improved functional as well as improved local solution, while the traditional dual energy method is possible to provide only the improved functional. Even if a single type of potential is required to implement the dual energy approach, this method has been compelled to solve the two-independent systems (Voronoi and Delaunay).

In this paper, we exploit the Voronoi-Delaunay transformation method that the solution of Delaunay system can be obtained by transforming the solution of Voronoi system. This means that only the Voronoi system of equations has to be solved to implement the dual energy approach. This Voronoi-Delaunay transformation method is now applied to the transient eddy current problems. As a result, it is found that the eddy current problems can be solved by means of the Voronoi-Delaunay transformation in an extremely efficient manner.

## VORONOI-DELAUNAY TRANSFORMATION METHOD

Basic field equation

In two dimensional x-y plane, most of the eddy current problems is reduced to solve a following equation

$$\frac{1}{\mu} \frac{\partial^2 A}{\partial x^2} + \frac{1}{\mu} \frac{\partial^2 A}{\partial y^2} - \sigma \frac{\partial A}{\partial t} = -J_s, \quad (1)$$

where  $A$ ,  $J_s$ ,  $\mu$  and  $\sigma$  are the z-component of vector potential, source current density, permeability and conductivity, respectively. The vector potential  $A$  is related with the flux density  $B$  by

$$\nabla \times A = B \quad , \quad (2)$$

so that the electric field intensity  $E$  is given by

$$E = -\nabla \phi - \frac{\partial A}{\partial t} \quad . \quad (3)$$

The scalar potential  $\phi$  and time derivative term in (3) are respectively related with the source current density  $J_s$  and eddy current density  $J_e$  as

$$J_s = -\sigma \nabla \phi \quad , \quad (4)$$

$$J_e = \sigma (\partial A / \partial t) \quad . \quad (5)$$

Voronoi-Delaunay diagram

Delaunay triangulation of arbitrary set of points is constructed by considering the properties of its geometrical dual i.e., the set of Voronoi polygons. Delaunay triangles are related to Voronoi polygons in that the circumcenters of Delaunay triangles are the vertices of the Voronoi polygons. Figure 1 shows the triangles in Delaunay mesh, and the Voronoi polygons associated with these Delaunay triangles are shown by dashed lines.

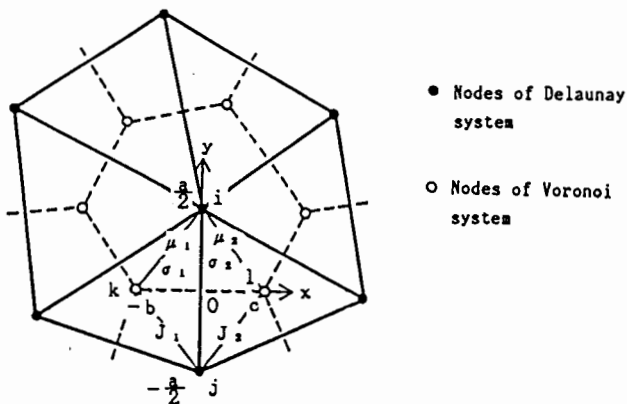


Fig.1.Voronoi-Delaunay diagram and a locally orthogonal coordinate system.

Locally orthogonal form

By considering Fig.1, it is obvious that the Delaunay triangles and Voronoi polygons are locally orthogonal : each triangle side is perpendicular to the corresponding Voronoi polygon edge. When we select a set of nodal variables  $A_i, A_j, A_k, A_l$ , then a following interpolating function may be assumed :

$$A = a_0 + a_1 x + a_2 y + a_3 x y \quad (6)$$

However, it is difficult to represent the coefficients  $a_0, a_1, a_2, a_3$  in terms of the nodal variables  $A_i, A_j, A_k, A_l$ , uniquely. This means that two complete but independent sets of nodal variables must be defined : one is located at the vertices of the Delaunay triangles ; and the other is located at the vertices of the Voronoi polygons. A simple Lagrange interpolation between the nodes  $i$  and  $j$  in Fig.1 yields a trial function for the Delaunay system as

$$A = (1/2)(A_i + A_j) + (A_i - A_j)(y/a) \quad (7)$$

where  $a$  is the distance between the nodes  $i$  and  $j$  (Saito et al., 1986, 1988, 1989). When we assume that each of the Delaunay triangles takes a distinct permeability  $\mu$ , then a flux density  $B_x [= \partial A / \partial y]$  must be continuous to both regions 1 and 2 in Fig.1. Equation (7) satisfies this boundary condition automatically. On the other side, a field intensity  $H_y [=- (1/\mu) \partial A / \partial x]$  must be common to both regions 1 and 2 in Fig.1. This boundary condition can be satisfied by the following interpolating functions between the nodes  $k$  and  $l$  in Fig.1 :

$$A = \{(A_k / \mu_1 b) + (A_l / \mu_2 c) + (A_l - A_k) x / (\mu_2 b c)\} / \{(1/\mu_1 b) + (1/\mu_2 c)\}, \quad -b \leq x \leq 0 \quad (8a)$$

$$A = \{(A_k / \mu_1 b) + (A_l / \mu_2 c) + (A_l - A_k) x / (\mu_1 b c)\} / \{(1/\mu_1 b) + (1/\mu_2 c)\}, \quad 0 \leq x \leq c \quad (8b)$$

where the distances  $b$  and  $c$  are shown in Fig.1 (Saito et al., 1986, 1988, 1989).

According to these two independent interpolating functions (7) and (8a)

or (8b), the governing equation (1) may be reduced to a one-dimensional equation in either the Delaunay or in the Voronoi sets of variables :

$$\frac{1}{\mu} \frac{\partial^2 A}{\partial x^2} = \frac{1}{2} \left[ \sigma \frac{\partial A}{\partial t} - J_s \right], \quad (9)$$

$$\frac{1}{\mu} \frac{\partial^2 A}{\partial y^2} = \frac{1}{2} \left[ \sigma \frac{\partial A}{\partial t} - J_s \right]. \quad (10)$$

### Functionals and nodal equations

A functional which automatically satisfies the  $B_x [= \partial A / \partial y]$  condition between the adjacent Delaunay triangles is given by

$$F(A) = \iint \left\{ (1/\mu) (\partial A / \partial y)^2 + [\sigma (\partial A / \partial t) - J_s] A \right\} dx dy. \quad (11)$$

After substituting Eq.(7) into Eq.(11) and integrating over the region enclosed by  $i-k-j-l$  in Fig.1, we can obtain the functional  $F(A)$  for the Delaunay system. By taking an extremum of this functional  $F(A)$ , a nodal equation for the node  $i$  in Fig.1 can be obtained as

$$\left( \frac{1}{\mu_1} \frac{b}{a} + \frac{1}{\mu_2} \frac{c}{a} \right) (A_i - A_j) + \frac{a}{2} (b \sigma_1 + c \sigma_2) \times \frac{\partial}{\partial t} (7A_i + 5A_j) = \frac{a}{4} (b J_1 + c J_2). \quad (12)$$

Entire Delaunay system of equations is represented by

$$D_D \Phi_D + E_D (d/dt) \Phi_D = F_D, \quad (13)$$

where  $D_D$ ,  $E_D$  are the coefficient matrices corresponding to the first and second terms on the left of Eq.(12);  $F_D$  is an input source current vector corresponding to the right of Eq.(12); and  $\Phi_D$  is the potential vector of Delaunay system, respectively.

On the other side, a functional which satisfied the  $H_y [= -(1/\mu) \partial A / \partial x]$  condition between the adjacent Delaunay triangles is given by

$$G(A) = - \iint \left\{ \mu (1/\mu) (\partial A / \partial x)^2 + [\sigma (\partial \hat{A} / \partial t) - J_s] \hat{A} \right\} dx dy. \quad (14)$$

where  $\hat{\phantom{a}}$  refers to the prescribed values.

After substituting Eqs.(8a) and (8b) into Eq.(14) and integrating over the region enclosing by  $i-k-j-l$  in Fig.1, we can obtain the functional  $G(A)$  for the Voronoi system. By taking an extremum of this functional  $G(A)$ , a nodal equation for the node  $k$  in Fig.1 can be obtained as

$$\begin{aligned} & [1 / (\mu_1 \frac{b}{a} + \mu_2 \frac{c}{a})] (A_k - A_1) + \frac{a b}{2} \sigma_1 \frac{\partial}{\partial t} A_k \\ & = \frac{a b}{2} J_1 . \end{aligned} \quad (15)$$

Entire Voronoi system of equations is represented by

$$D_v \Phi_v + E_v (d/dt) \Phi_v = F_v , \quad (16)$$

where  $D_v$ ,  $E_v$  are the coefficient matrices corresponding to the first and second terms on the left of Eq.(15);  $F_v$  is an input source current vector corresponding to the right term of Eq.(15); and  $\Phi_v$  is the potential vector of Voronoi system, respectively.

### Voronoi-Delaunay Transformation

The Voronoi system of equations has been derived satisfying with two boundary condition of tangential field intensity  $H_t$  between two adjacent Delaunay triangles. However, as shown in Fig.2(a), it is obvious that the normal components flux density  $B_n$  to the edges of Delaunay triangle are included in the entire solution of Voronoi system. The nodal variables which satisfy the boundary condition of normal flux density  $B_n$  are essentially located at the vertices of Delaunay triangle. A governing equation which must be satisfied by these nodal variables is given by

$$\frac{\partial}{\partial x} \left( \frac{1}{\mu} \right) \frac{\partial A}{\partial x} + \frac{\partial}{\partial y} \left( \frac{1}{\mu} \right) \frac{\partial A}{\partial y} = 0 , \quad (17)$$

where the current densities  $J_s$  and  $J_n$  in Eq.(1) have been lumped to the vertices of Voronoi polygons. Hence, by means of the Delaunay discretization (12), the vector potential  $A_1$  in Fig.2(b) can be represented in terms of the vector potentials of Voronoi system as

$$\begin{aligned}
 & [(1/\mu_1)\cot\alpha_1 + (1/\mu_2)\cot\beta_2]A_{k1} + [(1/\mu_2)\cot\alpha_2 \\
 & + (1/\mu_3)\cot\beta_3]A_{1n} + [(1/\mu_3)\cot\alpha_3 + (1/\mu_4)\cot\beta_4]A_{nq} \\
 & + [(1/\mu_4)\cot\alpha_4 + (1/\mu_5)\cot\beta_5]A_{qr} + [(1/\mu_5)\cot\alpha_5 \\
 & + (1/\mu_1)\cot\beta_1]A_{kr} = [\sum_{j=1}^5 (1/\mu_j)(\cot\alpha_j + \cot\beta_j)]A_1, \quad (18)
 \end{aligned}$$

where the angles  $\alpha_1 \sim \alpha_5$ ,  $\beta_1 \sim \beta_5$  are shown in Fig.2(b); and  $A_{k1}$ ,  $A_{1n}$ ,  $A_{nq}$ ,  $A_{qr}$ ,  $A_{kr}$  are the potential at the intersected points of Voronoi polygon and Delaunay triangle edges in Fig.2(b). For example  $A_{k1}$  is

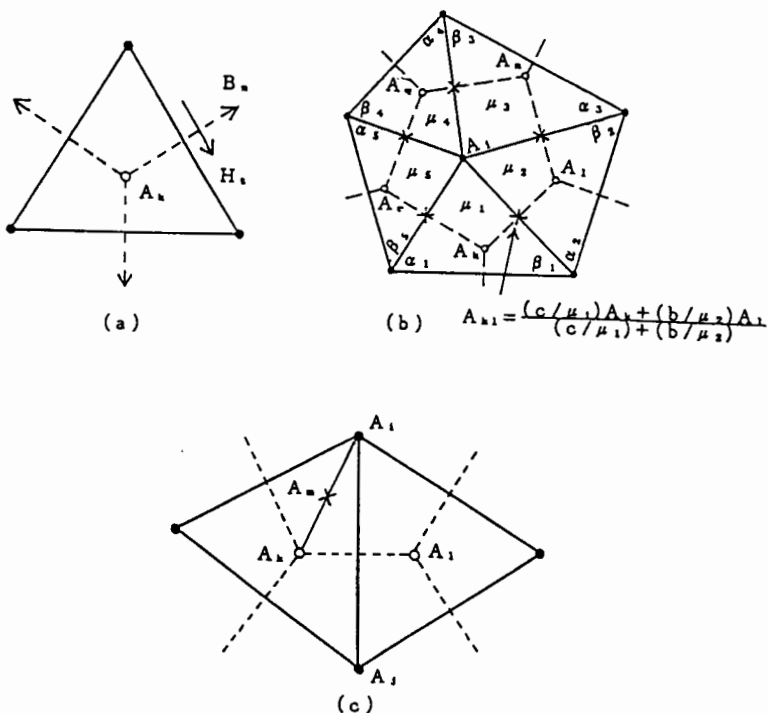


Fig.2. (a) The normal component of flux density  $B_n$  and tangential component of field intensity  $H_t$ . (b) Transformation from the Voronoi nodal variables to Delaunay nodal variables. (c) Location of the mid point potential  $A_n$ .



$$A_{k1} = [(c/\mu_1)A_k + (b/\mu_2)A_1] / [(c/\mu_1) + (b/\mu_2)]. \quad (19)$$

Thus, by means of Eq.(19), the potential vector  $\Phi_D$  of the Delaunay system can be represented in terms of the connection matrix  $C$  and the potential vector  $\Phi_V$  as

$$\Phi_D = C \Phi_V. \quad (20)$$

By means of Eq.(20), the Delaunay system of equations (13) is transformed into the Voronoi system by

$$C^T D_D C \Phi_V + C^T E_D C (d/dt) \Phi_V = C^T F_D, \quad (21)$$

where a superscript  $T$  refers to the transposed matrices. Thereby, a total Voronoi system of equation becomes

$$D \Phi_V + E (d/dt) \Phi_V = F, \quad (22)$$

where

$$D = (1/2)[C^T D_D C + D_V], \quad (23a)$$

$$E = (1/2)[C^T E_D C + E_V], \quad (23b)$$

$$F = (1/2)[C^T F_D + F_V]. \quad (23c)$$

A coefficient  $(1/2)$  in Eqs.(23a)-(23c) is required because a simple summation of Eqs.(16) and (20) duplicates the input source current vector. Each of the transient solution vector  $\Phi_D$ ,  $\Phi_V$  in Eqs.(13) and (16) exhibits a different behaviour depending on their system eigenvalues, but the solution vector  $\Phi_V$  in Eq.(22) exhibits their averaged behaviour. This means that a promising transient response of Eq.(1) may be computed by Eq.(22) even if a small number of nodes is employed. Further improvement of the solutions is possible when we consider the potentials located at the mid points between the vertices of Voronoi polygon and Delaunay triangle. The mid point potential vector  $\Phi_M$  can be represented in terms of the vectors  $\Phi_V$  and  $\Phi_D$  as

$$\Phi_M = C_{DM} \Phi_D + C_{VM} \Phi_V, \quad (24)$$

where  $C_{DM}$ ,  $C_{VM}$  are the interpolating matrices between the vertices of

Voronoi polygon and Delaunay triangle. For example, a mid point potential  $A_m$  in Fig.2(c) is given by

$$A_m = (1/2)A_i + (1/2)A_k . \quad (25)$$

By means of Eq.(20), Eq.(24) is reduced into

$$\Phi_M = (C_{DM}C + C_{VM})\Phi_V . \quad (26)$$

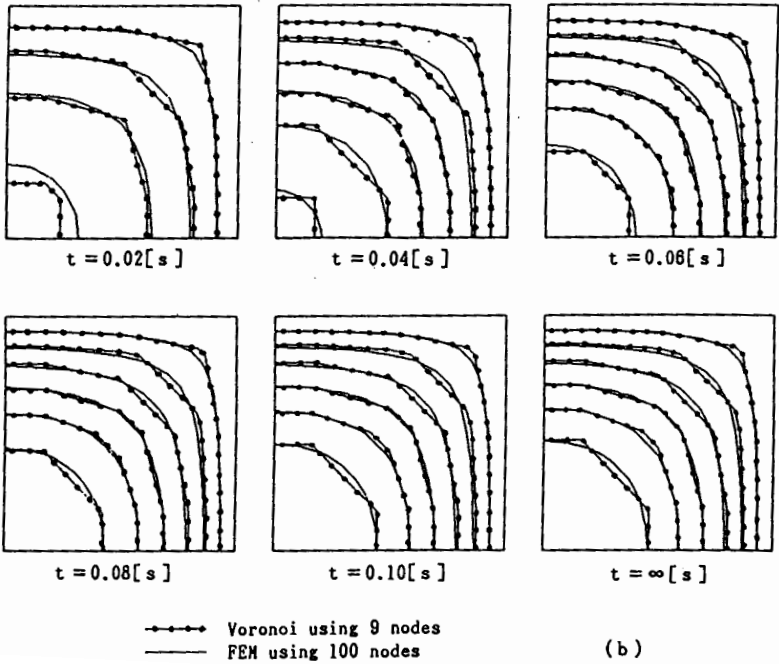
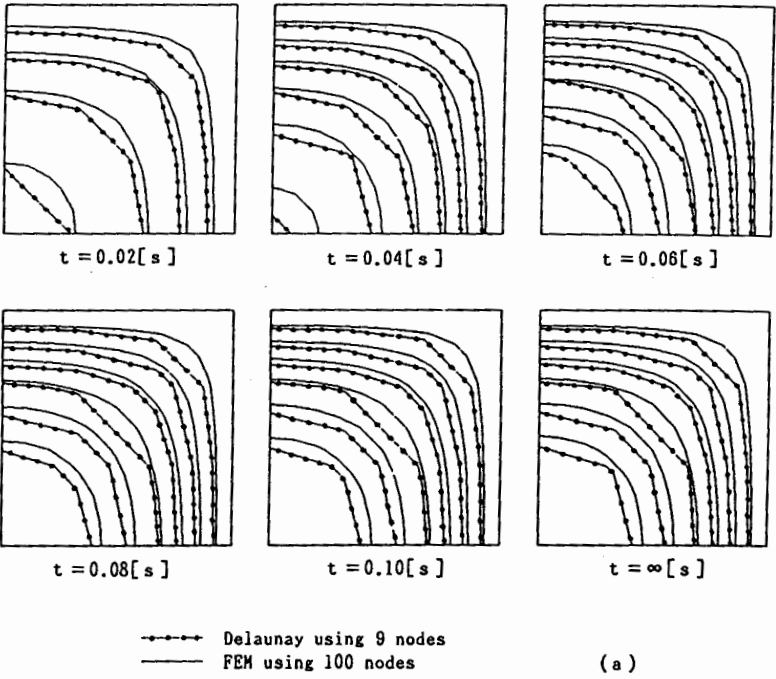
The potential vector  $\Phi_M$  in Eq.(26) is obviously improved in accuracy because the vector  $\Phi_M$  takes into account the boundary condition both of the tangential field intensity  $H_t$  and normal flux density  $B_n$  in Fig.2(a).

#### An example

The method is illustrated by applying to a dynamic magnetic field calculation of ferromagnetic material with square cross section (Saito *et al.*, 1986, 1988, 1989). The time discretization of Eq.(21) was carried out by the conventional trapezoidal method. Various constants used in the calculations are listed in Table 1. Figures 3(a) and 3(b) show the transient field distributions computed by the Delaunay (13) and Voronoi (16) systems, respectively. Figure 3(c) shows the results of computations obtained by the Voronoi-Delaunay transformation of Eqs.(22) and (26). For comparison, the solution computed by the standard first order triangular finite element method is also shown in these figures. By considering Figs.3(a)-3(c), it is obvious that our Voronoi-Delaunay transformation method provides an excellent result even if a small number of nodes is employed.

TABLE 1. Various constants used in the computations.

Permeability $\mu$	2.513[H/m]
Conductivity $\sigma$	20[1/ $\Omega$ -m]
Step source current density $J_s$	2[A/m <sup>2</sup> ]
Step width in time $\Delta t$	0.001[sec]



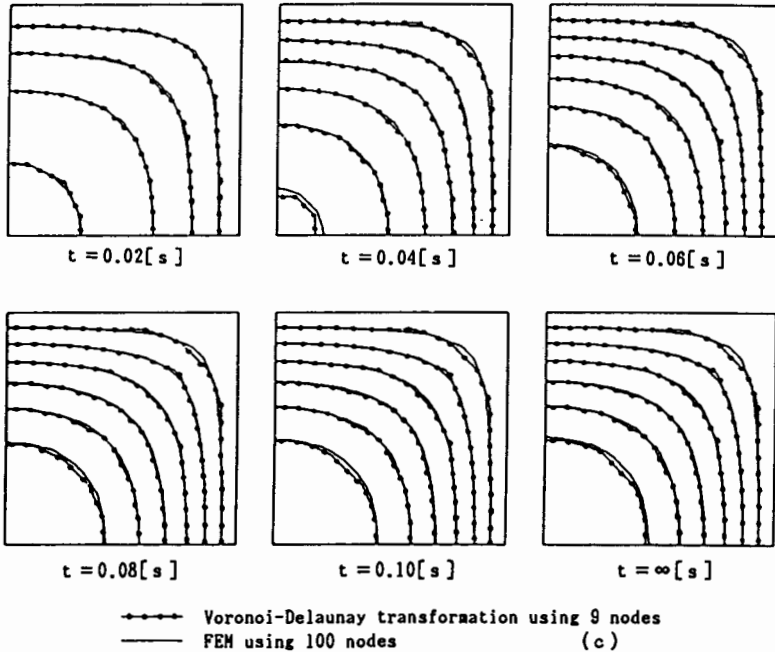


Fig.3. Transient field distributions computed by (a) the Delaunay (b) Voronoi (c) Voronoi-Delaunay transformation methods together with the standard first order triangular finite element method.

## CONCLUSION

Previously proposed locally orthogonal discretization method was a quite effective method to calculate the electromagnetic fields in an efficient manner, but it was compelled to solve the two independent systems i.e., Voronoi and Delaunay. To overcome this deficiency, we have proposed, in this paper, the Voronoi-Delaunay transformation method, which requires only one system of equations to implement a dual energy approach. As a result, it is revealed that the transient eddy current problems can be solved by our new method in an extremely efficient manner.

## REFERENCES

- Saito, Y., Y. Kishino, S. Hayano, H. Nakamura, N. Tsuya and Z.J. Cendes (1986). Faster magnetic field computation using locally orthogonal discretization. *IEEE Trans. Magn.*, Vol.MAG-22, No.5, 1057-1059.
- Saito, Y., Y. Kishino, k. Fukushima, S. Hayano and N. Tsuya (1988). Modeling magnetization characteristics and faster magnetodynamic field computation(invited). *J. Appl. Phys.*, 63(8), 3174-3178.
- Saito, Y., S. Ikeguchi and S. Hayano(1988). A meaningful post-processing method based on a locally orthogonal discretization. *J. Appl. Phys.*, 63(8), 3369-3371.
- Saito, Y., S.Ikeguchi and S. Hayano (to be appeared in January, 1989). An efficient computation of saturable magnetic field problem using locally orthogonal discretization. *IEEE Trans. Magn.*.
- Penman, J. and J.R. Fraser(1982). Complementary and dual energy finite element principles in magnetostatics. *IEEE Trans. Magn.*, Vol.MAG-18, No.2, 319-324.
- Hammond, P. and T.D. Tsiboukis(1983). Dual finite-element calculation for static electric and magnetic fields. *Proc. IEE*, Pt. A, Vol.130, No.3, 105-111.
- Hammond, P. and J. Penman (1983). Calculation of inductance and capacitance by means of dual energy principles. *Proc. IEE*. Vol.123, No.6, 554-559.